## Residual and fixed modules

Vasyl Petechuk, Yulia Petechuk

Let $V$ be an arbitrary $R$-module over an associative ring $R$ of $1, G L(V)$ is a group of automorphisms of module $V$.

The $R(\sigma)=(\sigma-1) V$ and $P(\sigma)=\operatorname{ker}(\sigma-1)$ respectively, are called residual and fixed submodules of the module $V$ of the endomorphism $\sigma$.

Inclusions system

$$
\left\{\begin{array}{l}
R\left(\sigma_{1}\right) \in P\left(\sigma_{2}\right) ;  \tag{1}\\
R\left(\sigma_{2}\right) \in P\left(\sigma_{1}\right)
\end{array}\right.
$$

exists if and only if $\left(\sigma_{1}-1\right)\left(\sigma_{2}-1\right)=\left(\sigma_{2}-1\right)\left(\sigma_{1}-1\right)=0$ otherwise when $\sigma_{1} \sigma_{2}=\sigma_{2} \sigma_{1}=\sigma_{1}+\sigma_{2}-1$.
It is clear that the commutativity $\sigma_{1} \sigma_{2}=\sigma_{2} \sigma_{1}$ follows from the system (1). On the contrary, it is not always true. It is easy to see that if $\sigma_{1} \sigma_{2}=\sigma_{2} \sigma_{1}$ and one of the inclusions of the system (1) takes place, then the second inclusion of system (1) also takes place. If $\sigma_{1} \sigma_{2}=\sigma_{2} \sigma_{1}$ and $R\left(\sigma_{1}\right) \bigcap R\left(\sigma_{2}\right)=0$ or $P\left(\sigma_{1}\right)+P\left(\sigma_{2}\right)=V$ then system (1) takes place. Finding other conditions for which of the commutativity $\sigma_{1}$ and $\sigma_{2}$ follows system (1) is the main purpose of the work.

Properties of residual and fixed submodules are used to describe homomorphisms of matrix groups over associative rings from $1[1]$. The method of residual and fixed subspaces was introduced by O'Meara. A shorter version of the proof of O'Meara-Sosnovskij theorem, which describes isomorphisms between full groups preserves projective transvections, has proposed by one of the authors in [3].

The basis of the method of residual and fixed subspaces is the two main properties of transvection. In particular, if $\sigma_{1}$ and $\sigma_{2}$ are transvections, then $\sigma_{1} \sigma_{2}=\sigma_{2} \sigma_{1}$ if and only if there is a system (1), and in the case where $R\left(\sigma_{1}\right) \subseteq R\left(\sigma_{2}\right)$ and $R\left(\sigma_{2}\right) \subseteq R\left(\sigma_{1}\right)$, then the commutator $\left[\sigma_{1}, \sigma_{2}\right]$ is a transvection with a residual subspace $R\left(\sigma_{1}\right)$ and a fixed subspace $P\left(\sigma_{2}\right)$.

In [2] it is proved that if R is a division ring, $V$ is a finite-dimensional vector space over $R, \operatorname{dim} R\left(\sigma_{1}\right)=\operatorname{dim} R\left(\sigma_{2}\right)=2, R\left(\sigma_{1}\right) \bigcap P\left(\sigma_{1}\right)=0, \sigma_{2}$ is a unipotent element of level 2 or $\operatorname{dim} R\left(\sigma_{1}\right)=2, R\left(\sigma_{1}\right) \bigcap P\left(\sigma_{1}\right) \neq 0, \sigma_{2}$ is a transvection then $\sigma_{1} \sigma_{2}=\sigma_{2} \sigma_{1}$ if and only if there is (1).

Authors are proven
Theorem. Let $R$ be a division ring, $V$ is a finite-dimensional vector space over $R$, $\operatorname{dim} R\left(\sigma_{1}\right) \bigcap P\left(\sigma_{1}\right) \neq \operatorname{dim} R\left(\sigma_{1}\right)-1, \sigma_{2}$ is a transvection. Equation $\sigma_{1} \sigma_{2}=\sigma_{2} \sigma_{1}$ is executed if and only if system (1) takes place.

The condition of the theorem on $\sigma_{1}$ means that $R\left(\sigma_{1}\right) \subseteq P\left(\sigma_{1}\right)$ or $R\left(\sigma_{1}\right) \cap P\left(\sigma_{1}\right)$ is a hyperplane in $R\left(\sigma_{1}\right)$.

We emphasize that if $\operatorname{dim} R\left(\sigma_{1}\right)<2$, then the conditions of the theorem are fulfilled automatically. If $\operatorname{dim} R\left(\sigma_{1}\right) \geq 2$, then without the assumption $\operatorname{dim} R\left(\sigma_{1}\right) \bigcap P\left(\sigma_{1}\right) \geq \operatorname{dim} R\left(\sigma_{1}\right)-1$ the theorem does not hold.

This shows an example $\sigma_{1}=\operatorname{diag}(\alpha, \ldots, \alpha, 1, \ldots, 1), \sigma_{2}=t_{1} k(1)$, where $\alpha$ is taken $k$ times, $\alpha \neq 0, \alpha \neq 1, k \geq 2$.

## References

1. V.M. Petechuk, Yu.V. Petechuk. Fixed and Residual Modules. Science News of Uzhgorod un-ty. Ser Math and inform 1 (30) (2017), 87-94.
2. A.I. Hahn, O.T. O'Meara The Classical Group and K-Theory. - Berlin: Springer, 1989.
3. V.M. Petechuk. Isomorphisms of groups of rich transvections. Math Notes. 2 (39) (1986), 186 -195.

Contact information
Vasyl Petechuk
Department of Mathematics and Informatics, Institute of Postgraduate Education, City Uzhgorod, Ukraine
Email address: vasil.petechuk@gmail.com

## Yulia Petechuk

Department of Mathematics and Informatics, Transcarpathian Hungarian Institute by Ferenc Rakoczy II, City Beregovo, Ukraine
Email address: vasil.petechuk@gmail.com
Key words and phrases. Residual and fixed modules, transvection, commutativ
Method of residual and fixed subspaces was introduced by O'Meara.

# Solvable Lie algebras of derivations of rank one 

Anatoliy Petravchuk, Kateryna Sysak

Let $\mathbb{K}$ be a field of characteristic zero and $A=\mathbb{K}\left[x_{1}, \ldots, x_{n}\right]$ the polynomial ring over $\mathbb{K}$. A $\mathbb{K}$ derivation $D$ of $A$ is a $\mathbb{K}$-linear mapping $D: A \rightarrow A$ that satisfies the rule: $D(a b)=D(a) b+a D(b)$ for all $a, b \in A$. The set $W_{n}(\mathbb{K})$ of all $\mathbb{K}$-derivations of the polynomial ring $A$ forms a Lie algebra over $\mathbb{K}$. This Lie algebra is simultaneously a free module over $A$ with the standard basis $\left\{\frac{\partial}{\partial x_{1}}, \frac{\partial}{\partial x_{2}}, \ldots, \frac{\partial}{\partial x_{n}}\right\}$. Therefore, for each subalgebra $L$ of $W_{n}(\mathbb{K})$ one can define the rank $\operatorname{rank}_{A} L$ of $L$ over the ring $A$. Note that for any $f \in A$ and $D \in W_{n}(\mathbb{K})$ a derivation $f D$ is defined by the rule: $f D(a)=f \cdot D(a)$ for all $a \in A$.

Finite dimensional subalgebras $L$ of $W_{n}(\mathbb{K})$ such that $\operatorname{rank}_{A} L=1$ were described in [1]. We study solvable subalgebras $L \subseteq W_{n}(\mathbb{K})$ of rank 1 over $A$ without restrictions on the dimension over the field $\mathbb{K}$.

Recall that a polynomial $f \in A$ is said to be a Darboux polynomial for a derivation $D \in W_{n}(\mathbb{K})$ if $f \neq 0$ and $D(f)=\lambda f$ for some polynomial $\lambda \in A$. The polynomial $\lambda$ is called the polynomial eigenvalue of $f$ for the derivation $D$. Some properties of Darboux polynomials and their applications in the theory of differential equations can be found in [3]. Denote by $A_{D}^{\lambda}$ the set of all Darboux polynomials for $D \in W_{n}(\mathbb{K})$ with the same polynomial eigenvalue $\lambda$ and of the zero polynomial. Obviously, the set $A_{D}^{\lambda}$ is a vector space over $\mathbb{K}$. If $V$ is a subspace of $A_{D}^{\lambda}$ for any derivation $D \in W_{n}(\mathbb{K})$, then we denote by $V D$ the set of all derivations $f D, f \in V$.

Theorem 1. Let $L$ be a subalgebra of the Lie algebra $W_{n}(\mathbb{K})$ of rank 1 over $A$ and $\operatorname{dim}_{\mathbb{K}} L \geq 2$. The Lie algebra $L$ is abelian if and only if there exist a derivation $D \in W_{n}(\mathbb{K})$ and a Darboux polynomial $f$ for $D$ with the polynomial eigenvalue $\lambda$ such that $L=V D$ for some $\mathbb{K}$-subspace $V \subseteq A_{D}^{\lambda}$.

Using this result one can characterize nonabelian subalgebras of rank 1 over $A$ of the Lie algebra $W_{n}(\mathbb{K})$. For the Lie algebra $\widetilde{W}_{n}(\mathbb{K})$ of all $\mathbb{K}$-derivations of the field $\mathbb{K}\left(x_{1}, x_{2}, \ldots, x_{n}\right)$ this problem is simpler and was considered in [2].

## References

1. I. V. Arzhantsev, E. A. Makedonskii, A. P. Petravchuk, Finite-dimensional subalgebras in polynomial Lie algebras of rank one, Ukrainian Math. Journal 63 (2011), no. 5, 827-832.
2. Ie. O. Makedonskyi, A. P. Petravchuk, On nilpotent and solvable Lie algebras of derivations, Journal of Algebra 401 (2014), 245-257.
