## Residual and fixed modules

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Let V be an arbitrary R-module over an associative ring R of 1, GL(V) is a group of automorphisms of module V.

The  $R(\sigma) = (\sigma - 1)V$  and  $P(\sigma) = ker(\sigma - 1)$  respectively, are called residual and fixed submodules of the module V of the endomorphism  $\sigma$ .

Inclusions system

$$\begin{cases}
R(\sigma_1) \in P(\sigma_2); \\
R(\sigma_2) \in P(\sigma_1)
\end{cases}$$
(1)

exists if and only if  $(\sigma_1 - 1)(\sigma_2 - 1) = (\sigma_2 - 1)(\sigma_1 - 1) = 0$  otherwise when  $\sigma_1 \sigma_2 = \sigma_2 \sigma_1 = \sigma_1 + \sigma_2 - 1$ .

It is clear that the commutativity  $\sigma_1\sigma_2 = \sigma_2\sigma_1$  follows from the system (1). On the contrary, it is not always true. It is easy to see that if  $\sigma_1\sigma_2 = \sigma_2\sigma_1$  and one of the inclusions of the system (1) takes place, then the second inclusion of system (1) also takes place. If  $\sigma_1\sigma_2 = \sigma_2\sigma_1$  and  $R(\sigma_1) \cap R(\sigma_2) = 0$  or  $P(\sigma_1) + P(\sigma_2) = V$  then system (1) takes place. Finding other conditions for which of the commutativity  $\sigma_1$  and  $\sigma_2$  follows system (1) is the main purpose of the work.

Properties of residual and fixed submodules are used to describe homomorphisms of matrix groups over associative rings from 1 [1]. The method of residual and fixed subspaces was introduced by O'Meara. A shorter version of the proof of O'Meara-Sosnovskij theorem, which describes isomorphisms between full groups preserves projective transvections, has proposed by one of the authors in [3].

The basis of the method of residual and fixed subspaces is the two main properties of transvection. In particular, if  $\sigma_1$  and  $\sigma_2$  are transvections, then  $\sigma_1\sigma_2 = \sigma_2\sigma_1$  if and only if there is a system (1), and in the case where  $R(\sigma_1) \subseteq R(\sigma_2)$  and  $R(\sigma_2) \subseteq R(\sigma_1)$ , then the commutator  $[\sigma_1, \sigma_2]$  is a transvection with a residual subspace  $R(\sigma_1)$  and a fixed subspace  $P(\sigma_2)$ .

In [2] it is proved that if R is a division ring, V is a finite-dimensional vector space over R,  $dimR(\sigma_1) = dimR(\sigma_2) = 2$ ,  $R(\sigma_1) \cap P(\sigma_1) = 0$ ,  $\sigma_2$  is a unipotent element of level 2 or  $dimR(\sigma_1) = 2$ ,  $R(\sigma_1) \cap P(\sigma_1) \neq 0$ ,  $\sigma_2$  is a transvection then  $\sigma_1 \sigma_2 = \sigma_2 \sigma_1$  if and only if there is (1).

Authors are proven

THEOREM. Let R be a division ring, V is a finite-dimensional vector space over R,  $dim R(\sigma_1) \cap P(\sigma_1) \neq dim R(\sigma_1) - 1$ ,  $\sigma_2$  is a transvection. Equation  $\sigma_1 \sigma_2 = \sigma_2 \sigma_1$  is executed if and only if system (1) takes place.

The condition of the theorem on  $\sigma_1$  means that  $R(\sigma_1) \subseteq P(\sigma_1)$  or  $R(\sigma_1) \cap P(\sigma_1)$  is a hyperplane in  $R(\sigma_1)$ .

We emphasize that if  $dimR(\sigma_1) < 2$ , then the conditions of the theorem are fulfilled automatically. If  $dimR(\sigma_1) \ge 2$ , then without the assumption  $dimR(\sigma_1) \cap P(\sigma_1) \ge dimR(\sigma_1) - 1$  the theorem does not hold.

This shows an example  $\sigma_1 = diag(\alpha, \dots, \alpha, 1, \dots, 1)$ ,  $\sigma_2 = t_1 k(1)$ , where  $\alpha$  is taken k times,  $\alpha \neq 0$ ,  $\alpha \neq 1$ ,  $k \geq 2$ .

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Method of residual and fixed subspaces was introduced by O'Meara.

# Solvable Lie algebras of derivations of rank one

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Let  $\mathbb{K}$  be a field of characteristic zero and  $A = \mathbb{K}[x_1, \dots, x_n]$  the polynomial ring over  $\mathbb{K}$ . A  $\mathbb{K}$ -derivation D of A is a  $\mathbb{K}$ -linear mapping  $D: A \to A$  that satisfies the rule: D(ab) = D(a)b + aD(b) for all  $a, b \in A$ . The set  $W_n(\mathbb{K})$  of all  $\mathbb{K}$ -derivations of the polynomial ring A forms a Lie algebra over  $\mathbb{K}$ . This Lie algebra is simultaneously a free module over A with the standard basis  $\{\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, \dots, \frac{\partial}{\partial x_n}\}$ . Therefore, for each subalgebra L of  $W_n(\mathbb{K})$  one can define the rank rank AL of L over the ring A. Note that for any  $f \in A$  and  $D \in W_n(\mathbb{K})$  a derivation fD is defined by the rule:  $fD(a) = f \cdot D(a)$  for all  $a \in A$ .

Finite dimensional subalgebras L of  $W_n(\mathbb{K})$  such that rank AL = 1 were described in [1]. We study solvable subalgebras  $L \subseteq W_n(\mathbb{K})$  of rank 1 over A without restrictions on the dimension over the field  $\mathbb{K}$ .

Recall that a polynomial  $f \in A$  is said to be a Darboux polynomial for a derivation  $D \in W_n(\mathbb{K})$  if  $f \neq 0$  and  $D(f) = \lambda f$  for some polynomial  $\lambda \in A$ . The polynomial  $\lambda$  is called the polynomial eigenvalue of f for the derivation D. Some properties of Darboux polynomials and their applications in the theory of differential equations can be found in [3]. Denote by  $A_D^{\lambda}$  the set of all Darboux polynomials for  $D \in W_n(\mathbb{K})$  with the same polynomial eigenvalue  $\lambda$  and of the zero polynomial. Obviously, the set  $A_D^{\lambda}$  is a vector space over  $\mathbb{K}$ . If V is a subspace of  $A_D^{\lambda}$  for any derivation  $D \in W_n(\mathbb{K})$ , then we denote by VD the set of all derivations fD,  $f \in V$ .

THEOREM 1. Let L be a subalgebra of the Lie algebra  $W_n(\mathbb{K})$  of rank 1 over A and  $\dim_{\mathbb{K}} L \geq 2$ . The Lie algebra L is abelian if and only if there exist a derivation  $D \in W_n(\mathbb{K})$  and a Darboux polynomial f for D with the polynomial eigenvalue  $\lambda$  such that L = VD for some  $\mathbb{K}$ -subspace  $V \subseteq A_D^{\lambda}$ .

Using this result one can characterize nonabelian subalgebras of rank 1 over A of the Lie algebra  $W_n(\mathbb{K})$ . For the Lie algebra  $\widetilde{W}_n(\mathbb{K})$  of all  $\mathbb{K}$ -derivations of the field  $\mathbb{K}(x_1, x_2, \ldots, x_n)$  this problem is simpler and was considered in [2].

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